
Visualization of Evolutionary Algorithms

- Set of Standard Techniques and Multidimensional Visualization

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Overview

- Motivation
- Standard set of visualization techniques
- Advanced method for multidimensional data
- Summary and Outlook

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Motivation

Introduction

Evolutionary Algorithms

- work with simple algorithms
- produce vast amount of data

Problem:

extraction of useful information to provide insight into

- state of the population,
- progress of the Evolutionary Algorithm

 **Visualization of data**

Goals:

- set of standard methods for different data types,
- advanced method for multidimensional data
- use of standard visualization methods and tools (MATLAB)

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Motivation

Data types

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Data types in Evolutionary Algorithms

- individuals (solution vector)
 - variables
 - objective value(s)
- (sub) populations
 - individuals
(variables / objective values of best / all individuals)
 - distance between individuals
 - ranking / order and size of subpopulations
- different time frame
 - one generation  state of EA
 - multiple / all generations  course of EA
 - multiple runs  comparison of EA

Standard set

Overview

Visualization of the **course** of the EA

- objective value of best individual of every generation (convergence diagram)
- variables of best individual of every generation
- objective value of all individuals of every generation

Visualization of the **state** of the EA

- objective value of all individuals
- variables of all individuals
- (distance map of objective values / variable values)

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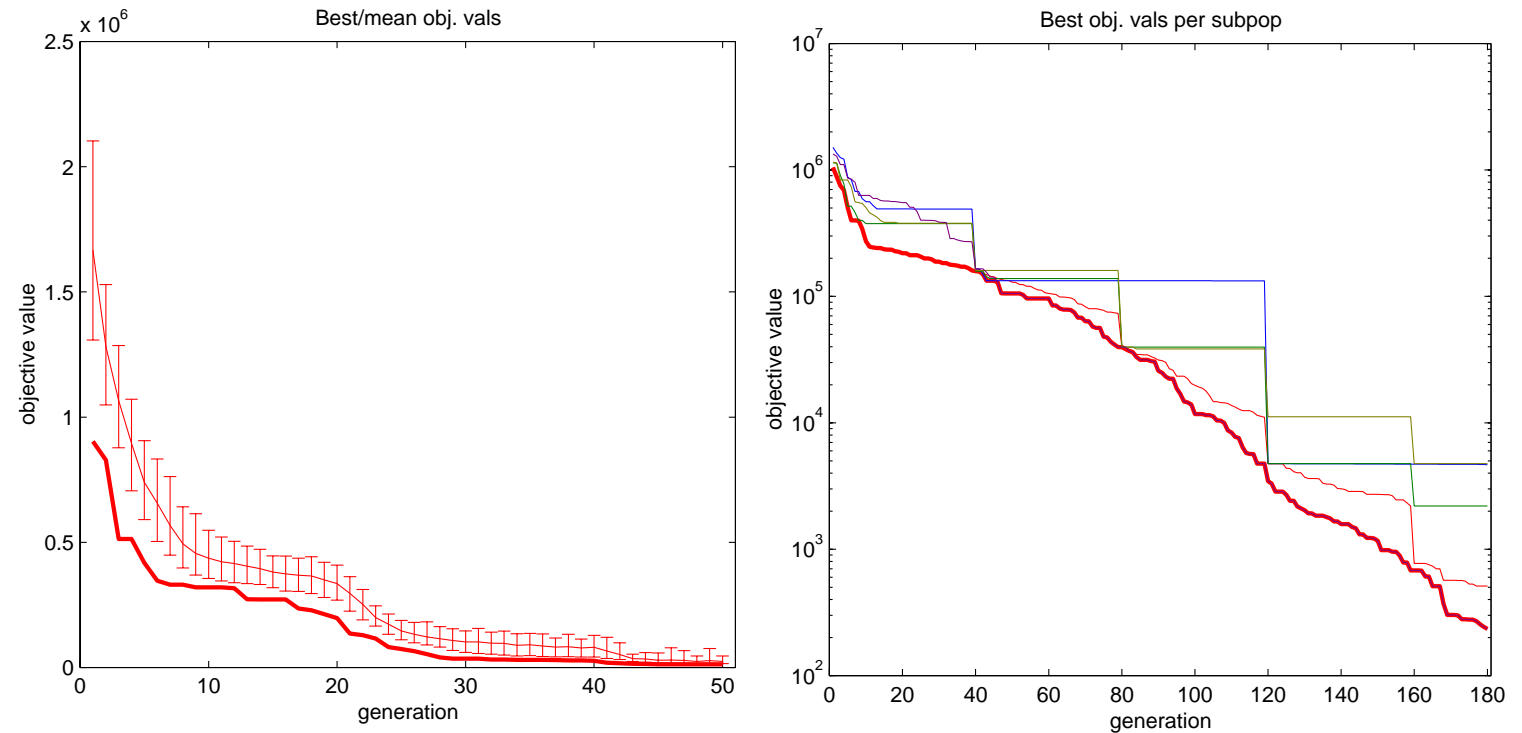
Standard set

Course - best objective value

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Objective value of best individuals (convergence)



- very often used
- visual impression of convergence (depends on scaling)
- extension for regional population model and for use of different strategies (right diagram)

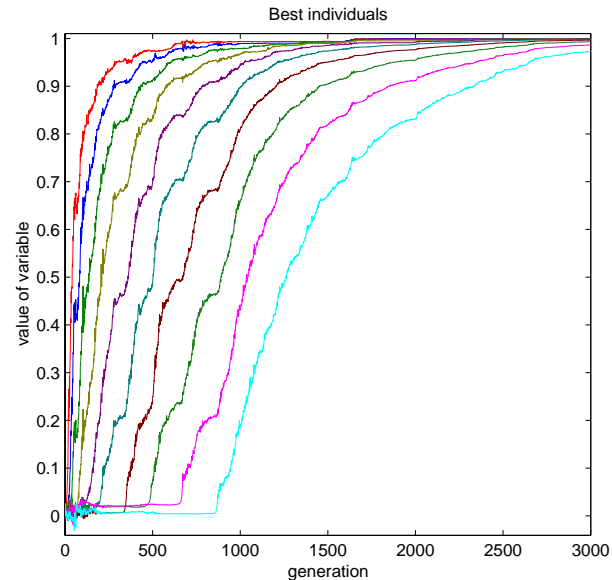
Standard set

Course - variables of best individual

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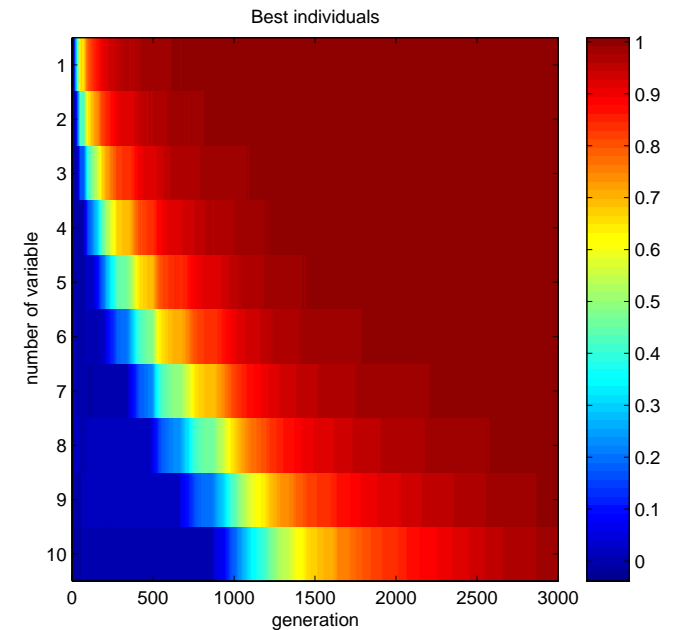
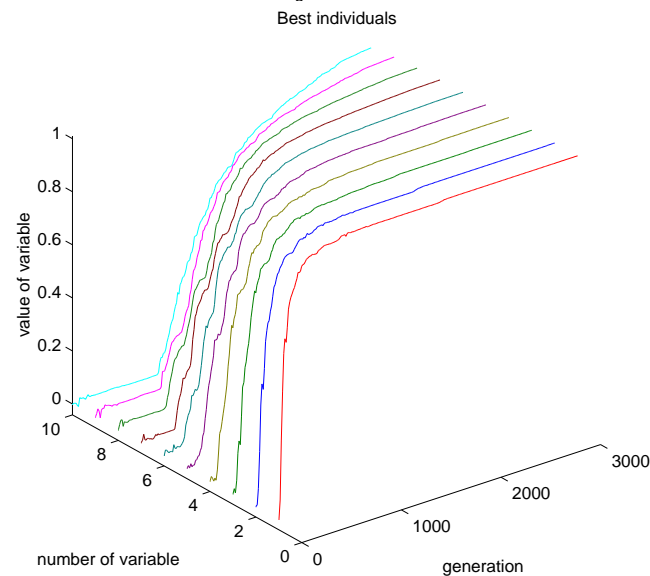
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Variables of best individual (all generations)



- one of the most representative graphics
- visualization of variable changes
- visualization of successful variables

(ROSENBROCK's function)



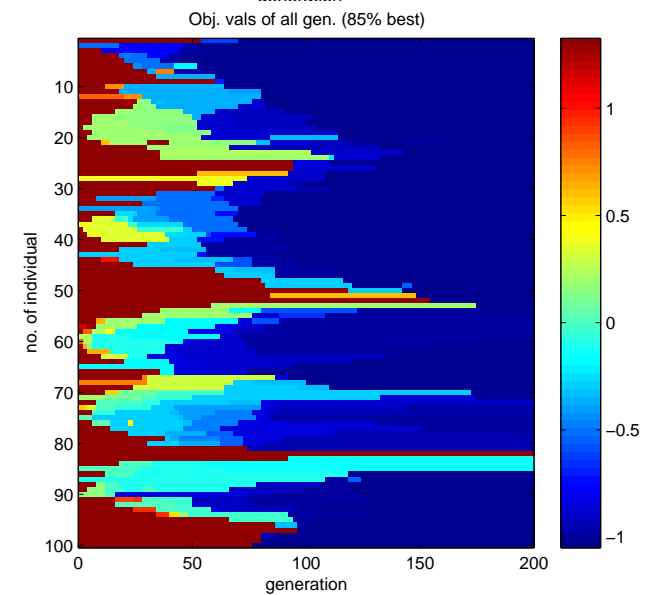
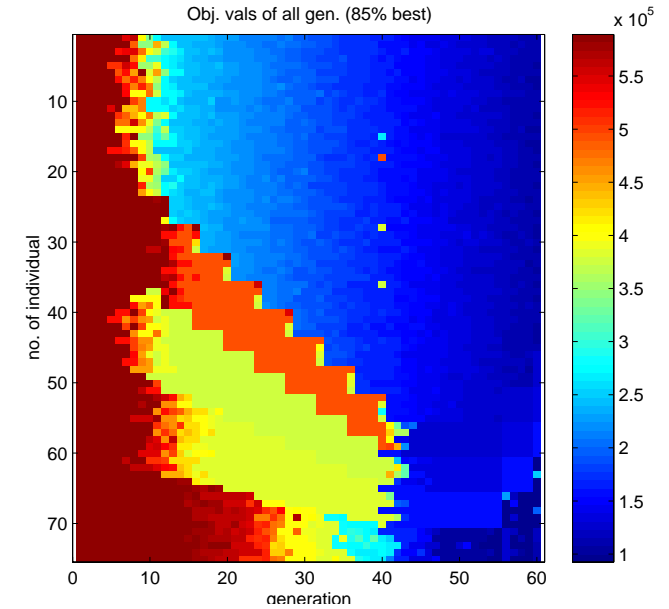
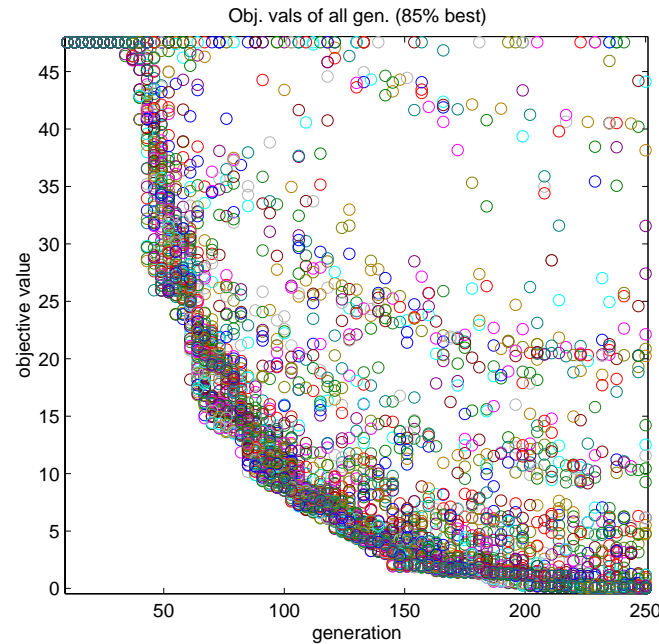
Standard set

Course - all objective values

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Objective values of all individuals (all generations)



- overview of population during one run
- extensions for
 - regional population model
 - local population model

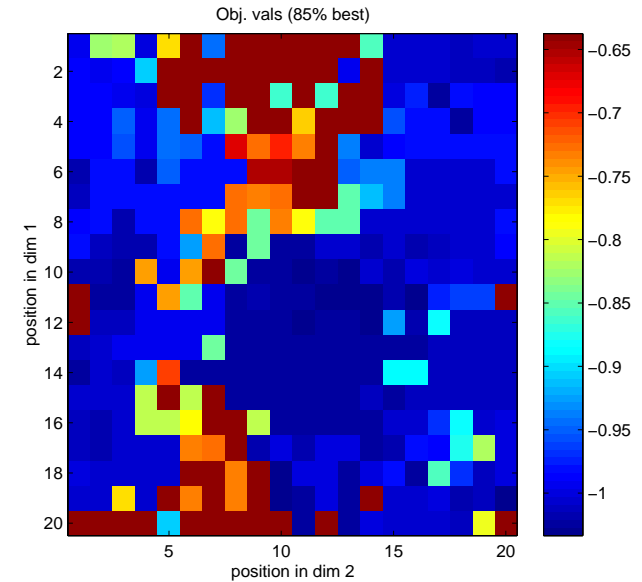
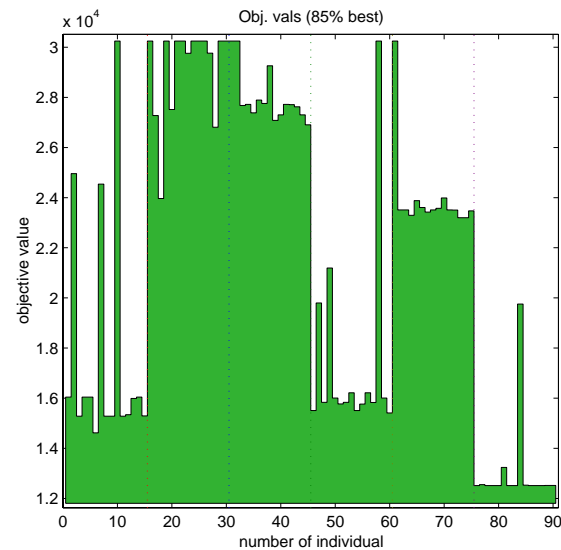
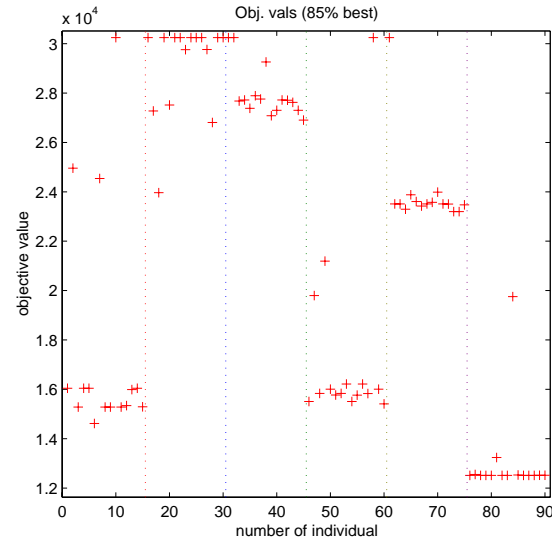
Standard set

State -
all objective
values

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All objective values (one generation)

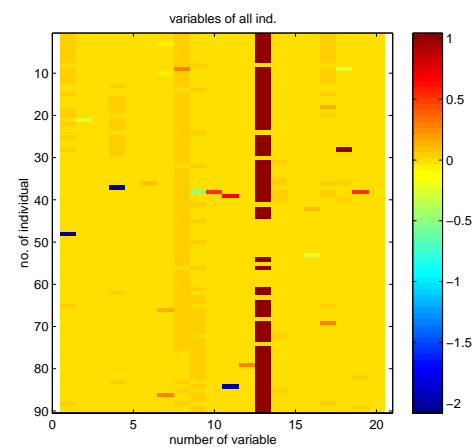
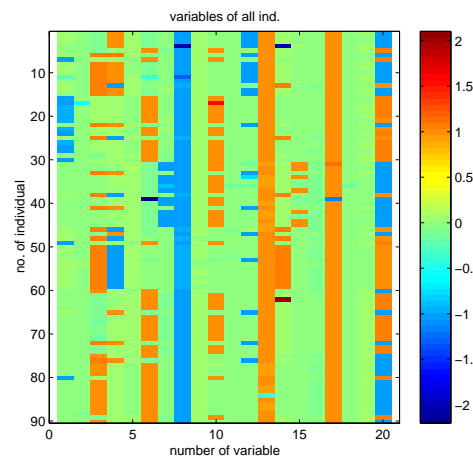
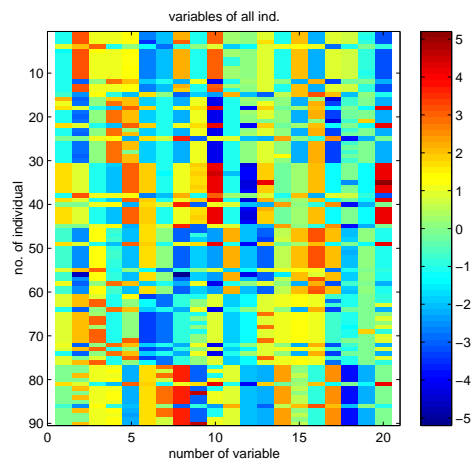
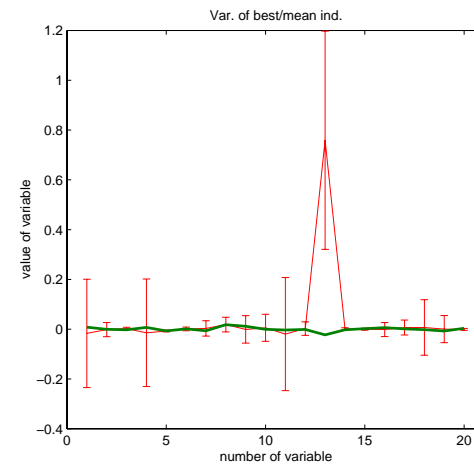
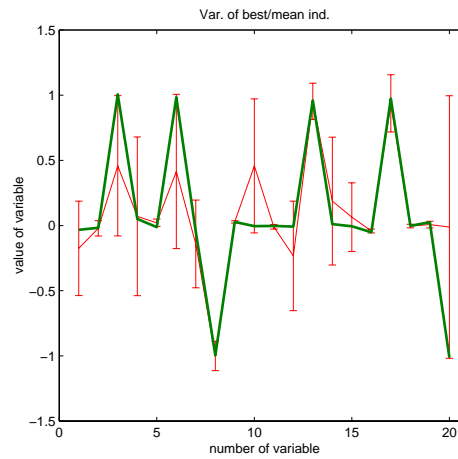
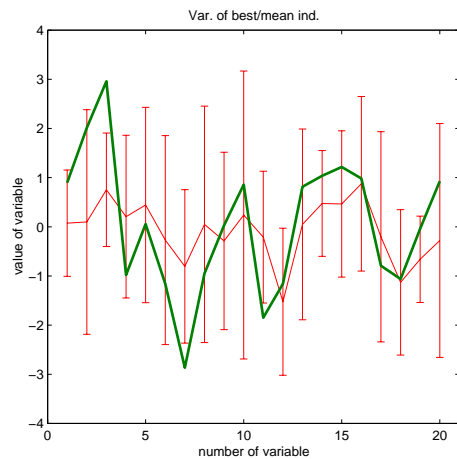


- visual impression of the state of the population
- extension for regional and local model

Variables of all individuals (one generation)

Standard set

State - variables of all individuals



- visual impression of the state of the population

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Advanced visualization

Motivation

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Visualization of high-dimensional data

Motivation

- limitation for standard visualization to three dimensions
- extension to 4 or 5 dimensions is difficult to use
(color and time)

Problem:

- transformation of multidimensional data to a lower dimension (2 or 3 dimensions)
 - preserve dissimilarities between data points
 - minimization of error of transformation

 'multidimensional scaling'

Advanced visualization

Dissimilarities

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Multidimensional scaling

- Dissimilarities

→ distance between points (Euclidean distance)

x_1, \dots, x_n : data points in \mathbb{R}^p δ_{ij} : distance between x_i and x_j

y_1, \dots, y_n : data points in \mathbb{R}^q , $p \geq q$ d_{ij} : distance between y_i and y_j

- search for a low-dimensional configuration, with

→ distances between data points similar to distances in high-dimensional configuration

→ quality criterion:
$$J_{ef} = \frac{1}{\sum_{i < j} \delta_{ij}} \sum_{i < j} \frac{(d_{ij} - \delta_{ij})^2}{\delta_{ij}}$$

$$\nabla_{y_k} J_{ef} = \frac{2}{\sum_{i < j} \delta_{ij}} \sum_{j \neq k} \left(\frac{d_{kj} - \delta_{kj}}{\delta_{kj}} \cdot \frac{y_k - y_j}{d_{kj}} \right)$$

- optimization by:

→ gradient based optimization (from Matlab)

→ more robust search: RPROP - only change of sign of gradient

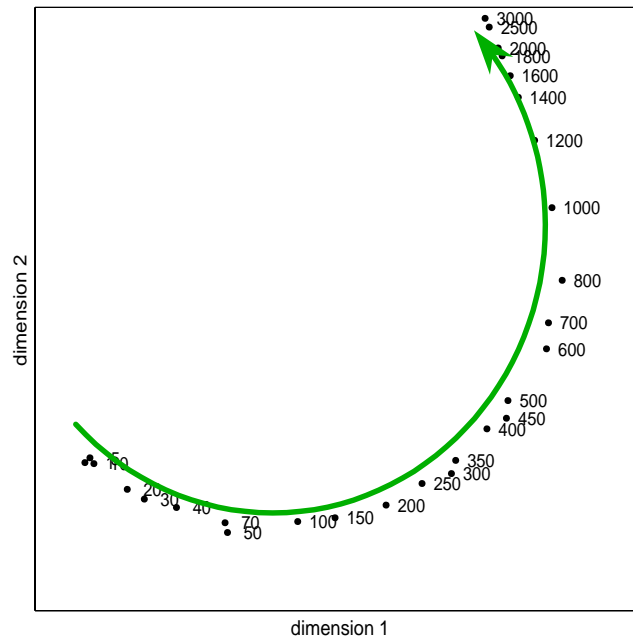
Advanced visualization

Example

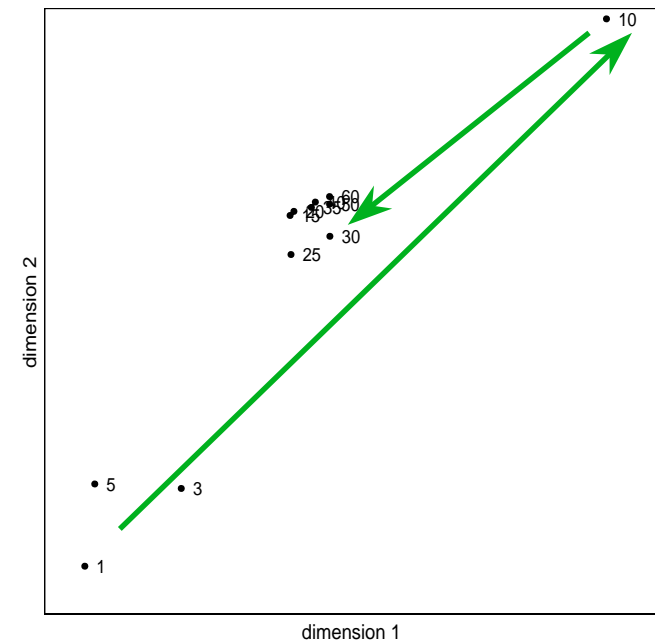
Variables of best individual

- “path through search space” of best individual
- additional information compared to standard plot
- better understandable picture than standard plot

Sammon-Mapping: best individuals (ROSENBRÖCK's Funktion 2)



Sammon-Mapping: variables of best individuals Chopper (Nr. 45)



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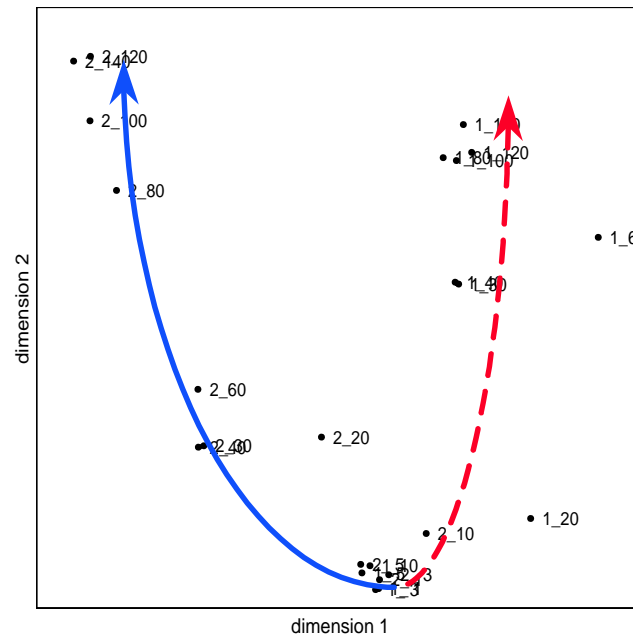
Advanced visualization

Example

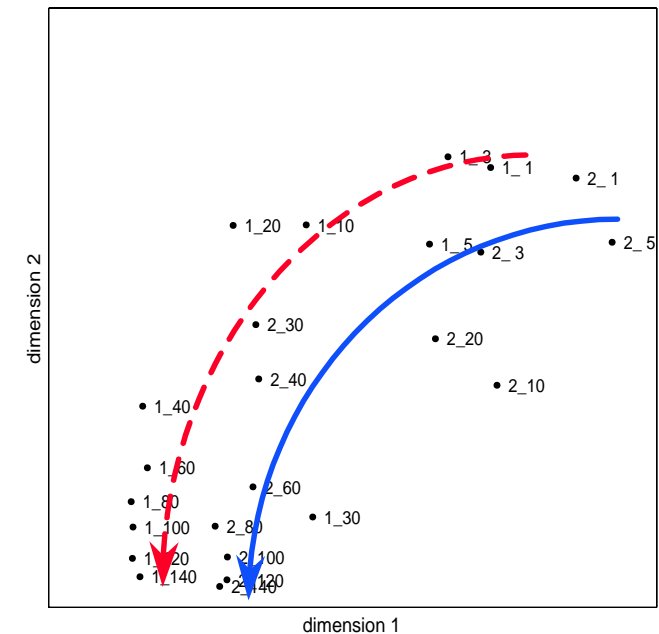
Comparing two optimization runs

- comparing optimization runs
 - variables of best individuals ("path through search space")
 - multi criteria objective values ("path through solution space")
1. run: **red paths** 2. run: **blue paths**

Sammon-Mapping: comparison variables of best individuals Chopper (Nr. 54 and 55)



Sammon-Mapping: comparison best objective values Chopper (Nr. 54 and 55)



Summary

Advantages

- Proposal of set of visualization methods

- methods for the course / progress of the EA
- methods for the state of the population
- methods for high-dimensional visualization

Advantages:

- baseline for understanding the evolutionary process
- insight into the work of the Evolutionary Algorithm
- powerful visualization tools to aid the designer and user of Evolutionary Algorithms

- application to real world problems proved successful

- example implementation

“Genetic and Evolutionary Algorithm Toolbox for use with Matlab”

<http://www.geatbx.com/index.html>

Application

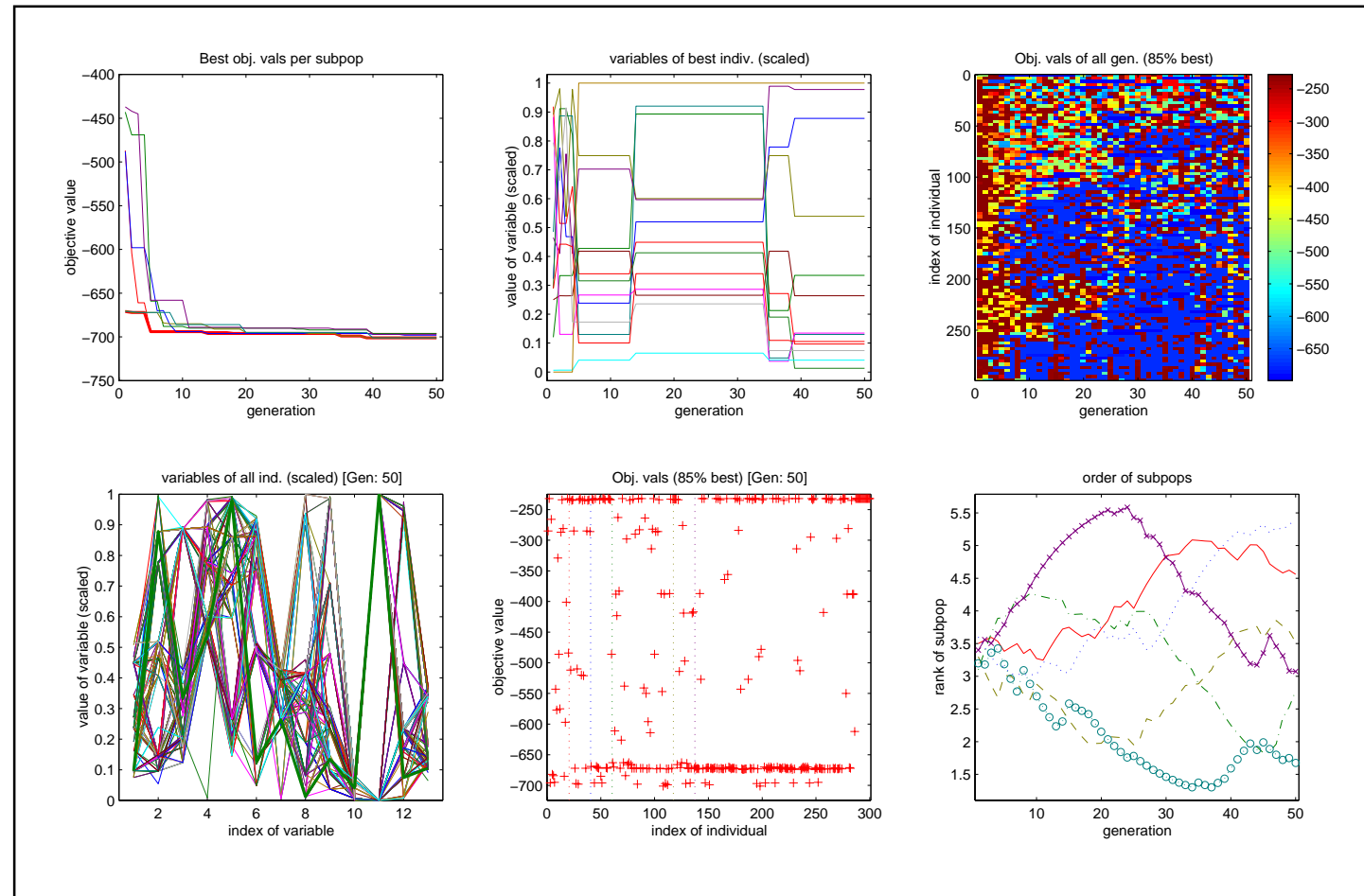
Real world system

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Application to real world problems

- Use of visualization methods for analysis of optimization run (optimization of real time system for maximal run time)



Application

Graphical user interface

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Graphical User Interface for visualization methods

- access to all visualization methods and styles during and after an optimization (corresponds with diagram on previous slide)

Output / Visualization

Course of optimization		State of population	
Best ObjV.	<input checked="" type="checkbox"/>	5: 2-D line for every sub	<input type="checkbox"/>
Var best ind.	<input checked="" type="checkbox"/>	6: same as 1, scaled va	<input type="checkbox"/>
All ObjV.	<input checked="" type="checkbox"/>	4: image plot: all objv.	<input type="checkbox"/>
Size Subpop	<input checked="" type="checkbox"/>	3: 2-D line: position of st	<input type="checkbox"/>
All ObjV.	<input checked="" type="checkbox"/>	1: 2-D point: all objv (85	<input type="checkbox"/>
All Variables	<input checked="" type="checkbox"/>	6: same as 1, scaled va	<input type="checkbox"/>
Distance	<input type="checkbox"/>	1: 2-D stairs: between a	<input type="checkbox"/>

Data file name:

Start Generation:

End Generation: